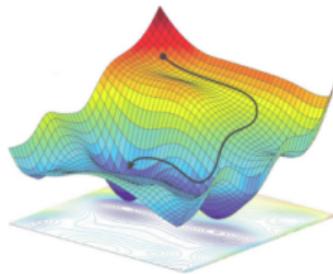


# A new multi-objective calibration R package for SWAT and SWAT+ models

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# Why do we need multi-objective optimisation?

## Limitations of single-objective calibration

- The application of single-objective algorithms leads to **equifinality** (Beven, 1993), where multiple parameter sets can produce equally good model outputs.
- No single-objective function is able to capture all the **interactions** between model output variables and its observed counterparts (Yapo et al., 1998; Wagener, 2003).

## Advantages of multi-objective calibration

- Multi-objective calibration is able to **exploit all of the information about the physical system** contained in the observed time series (Yapo et al., 1998) (e.g., Q, SM, ET, GPP, NO<sub>3</sub>).
- Using several model outputs **reduces parametric and model output uncertainties** → more reliable model predictions (Efstratiadis and Koutsoyiannis, 2010).



# Why do we need a new MO calibration software?

- Most of the publicly available calibration software still relies on single-objective (SO) optimisation algorithms (SCE\_UA, SA, DE, PSO).
- There are several multi-objective optimisation algorithms available, including MOSCEM, NSGA-II, MOPSO, MEAS, SPEA (Efstratiadis and Koutsoyiannis, 2010).
- Publicly available multi-objective optimisation software are not designed to calibrate hydrological models, e.g., `pymoo` (Blank and Deb, 2020), `rmooc` (Benitez and Pinto-Roa, 2022).
- To the best of our knowledge the only model-oriented software publicly available is `caRamel` (Monteil et al., 2020), which is not model-independent.

∴ There is a lack of flexible multi-objective optimisation software that can be easily coupled with a user-defined hydrological model (e.g., SWAT+).



# hydroMOPSO - General description

- Is a new [R package](#) for multi-objective calibration of environmental/hydrological models, specifically designed to calibrate real-world models.
- Is inspired and closely follows the philosophy of the single objective [hydroPSO](#) R package (Zambrano-Bigiarini and Rojas, 2013), which has been applied to a wide variety of models.
- Is based on the [NMPSO algorithm](#) (Lin et al., 2016, 2015), which combines two search mechanisms (PSO and genetic operators) to maintain the [population's diversity](#) and [accelerate its convergence](#) towards the Pareto-optimal set.



# hydroMOPSO - Main features:

- **Model-independent:** can be used to calibrate **R-based models** (e.g., TUWmodel, GR-models) and **R-external models** (e.g., SWAT+, SWAT, Raven, WEAP, MODFLOW).
- **Platform-independent:** It can be run in **GNU/Linux**, **MacOS** and **Windows** machines.
- **Computationally efficient:** It takes advantage of **multi-core machines** and **network clusters** → important reduction of execution time.
- **Highly configurable:** It has several **fine-tuning options** and an effective default configuration. (Marinao-Rivas and Zambrano-Bigiarini, 2021).

The package is already available on CRAN (<https://cran.r-project.org/package=hydroMOPSO>)

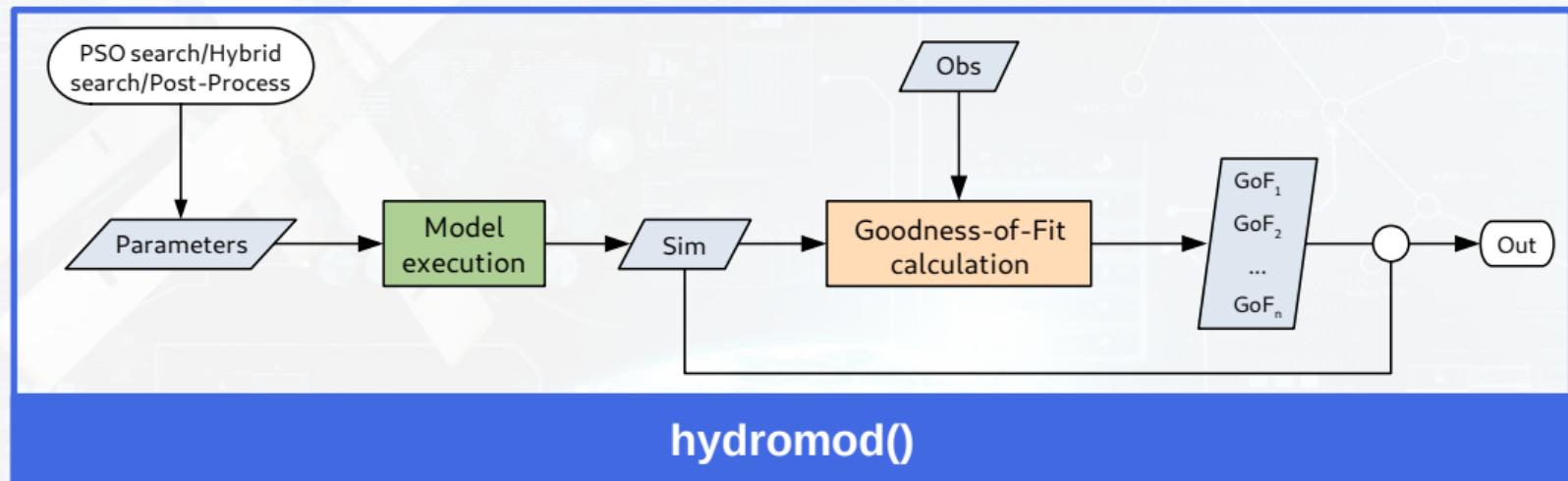


# hydroMOPSO: Main functions

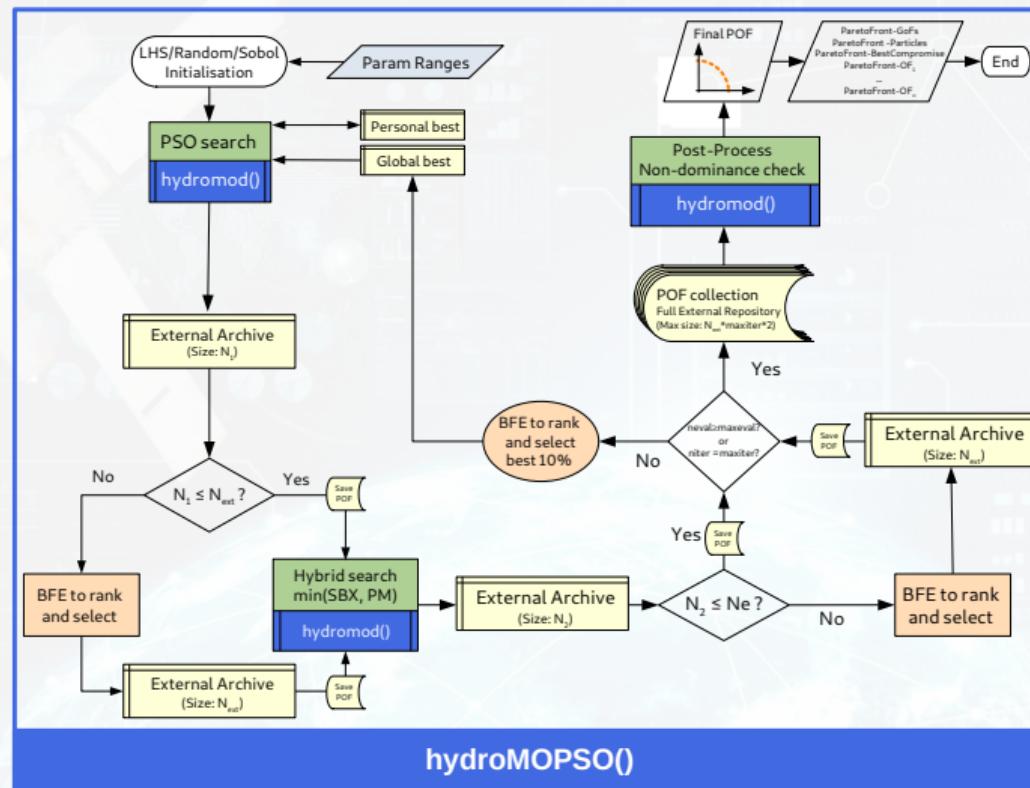
- **hydromod**: Runs the model to be calibrated using its **executable file** (e.g., SWATplus\_rev60.5.4.exe) and a **single parameter set**.  
For SWAT and SWAT+, it requires the definition of two additional files:  
ParameterRanges.txt, and ParameterFiles.txt,
- **hydroMOPSO**: Runs the multi-objective calibration of the user-defined model (e.g., SWAT+)
- **ReadResults**: Reads all the output files created by hydroMOPSO (e.g., POF, GoFs, Best Compromise Solution)
- **PlotResults**: Plots the results of the multi-objective calibration (POF, dotty plots, observations1 vs simulations1, etc).



# hydromod function - flowchart



# hydroMOPSO function - flowchart



hydroMOPSO()

(CR)<sup>2</sup>



# Additional files required for SWAT/SWAT+:

To make parameter changes in SWAT/SWT+, the user needs to prepare two files:

- **ParamRanges.txt**: Indicates the **physical ranges** used to calibrate each parameter.
- **ParamFiles.txt**: Indicates the **name of the input files that stores the parameters** being calibrated and the type of change (abs, rel, add).

**ParamFiles.txt**

ParameterNmbr	ParameterName	Filename	Row.Number	Col.Start	Col.End	DecimalPlaces	TypeChange	RefValue	MinValue	MaxValue
1	par_1	file_1	x_1	y_1	z_1	dec_1	typ_1	ref_1	min_1	max_1
2	par_2	file_2	x_2	y_2	z_2	dec_2	typ_2	ref_2	min_2	max_2
3	par_3	file_3	x_3	y_3	z_3	dec_3	typ_3	ref_3	min_3	max_3
4	par_4	file_4	x_4	y_4	z_4	dec_4	typ_4	ref_4	min_4	max_4
.	.	.	.	.	.	.	.	.	.	.
.	.	.	.	.	.	.	.	.	.	.
n	par_n	file_m	x_n	y_n	z_n	dec_n	typ_n	ref_n	min_n	max_n

**ParamRanges.txt**

ParameterNmbr	ParameterName	MinValue	MaxValue
1	par_1	minval_1	maxval_1
2	par_2	minval_2	maxval_2
3	par_3	minval_3	maxval_3
4	par_4	minval_4	maxval_4
.	.	.	.
.	.	.	.
n	par_n	minval_n	maxval_n



# Wrapper function to run SWAT/SWAT+:

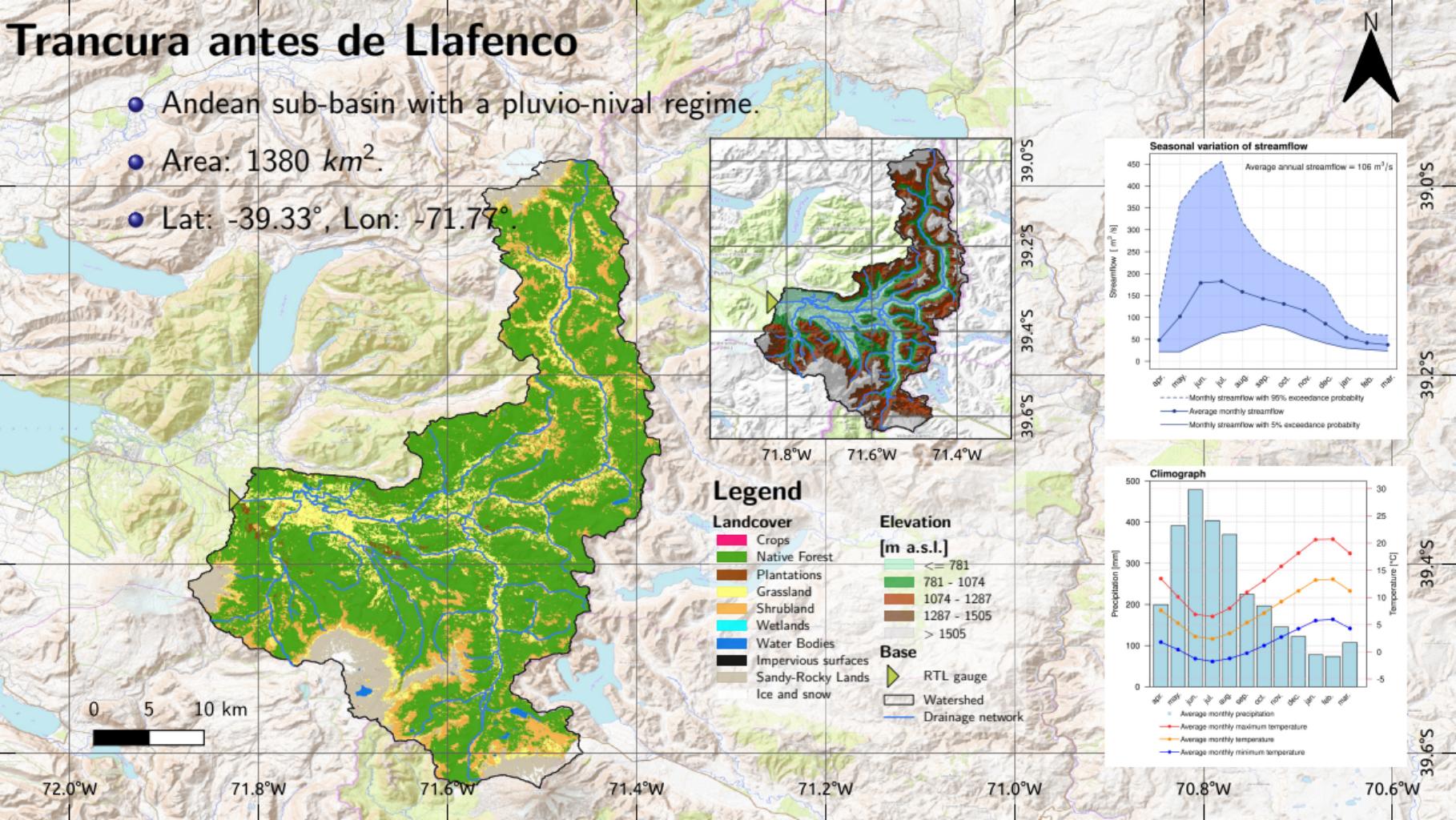
A minimal example of the wrapper function to run SWAT/SWAT+:

```
1 Wrapper4SWATplus <- function(param.values, obs, ...){  
2   # Running SWAT+  
3   sim <- hydromod(param.values = param.values,  
4                     exe.fname = "./SWATplus_rev60.5.4.sh", ...)  
5  
6   # Getting simulated variables  
7   sim.var1 <- sim[[1]] # simulated variable 1  
8   sim.var2 <- sim[[2]] # simulated variable 2  
9  
10  # Getting observations (from user-defined input files)  
11  obs.var1 <- obs[[1]] # observed variable 1  
12  obs.var1 <- obs[[2]] # observed variable 2  
13  
14  # Calculating 2 goodness-of-fit measures:  
15  gof1 <- KGE(sim = sim.var1, obs = obs.var1) # GoF for variable 1  
16  gof2 <- NSE(sim = sim.var2, obs = obs.var2) # GoF for variable 2  
17  
18  # Outputs to be returned to hydroMOPSO  
19  out[[1]] <- list(gofs = c(gof1, gof2),  
20                    sims = list(sim.var1, sim.var2))  
21  return(out)  
22}
```



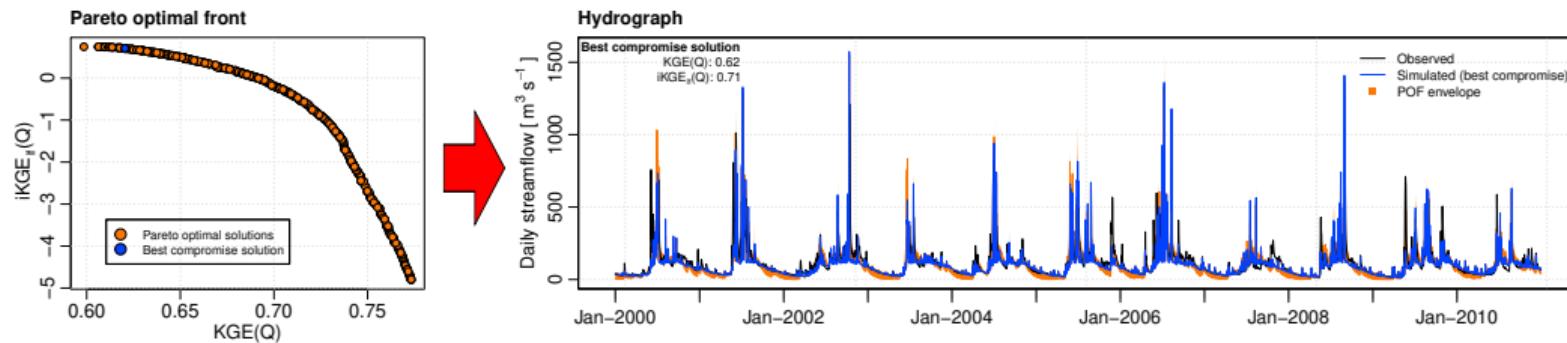
## **Trancura antes de Llafenco**

- Andean sub-basin with a pluvio-nival regime.
  - Area:  $1380 \text{ km}^2$ .
  - Lat:  $-39.33^\circ$ , Lon:  $-71.77^\circ$ .



# Example 1: Two different objective functions (OF)

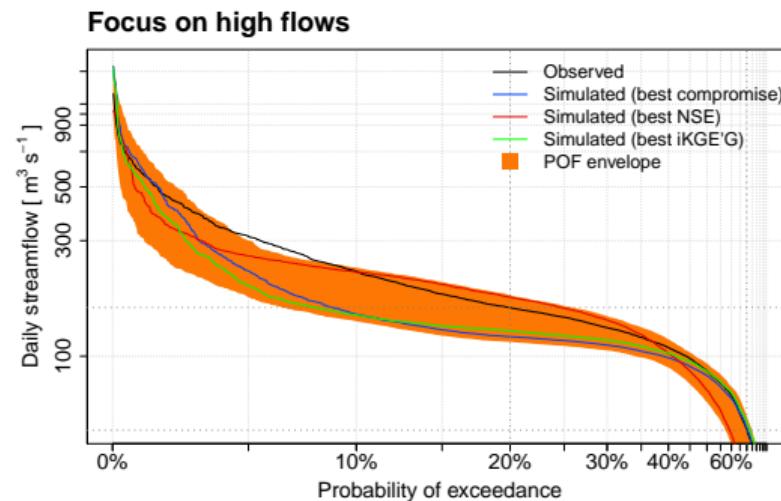
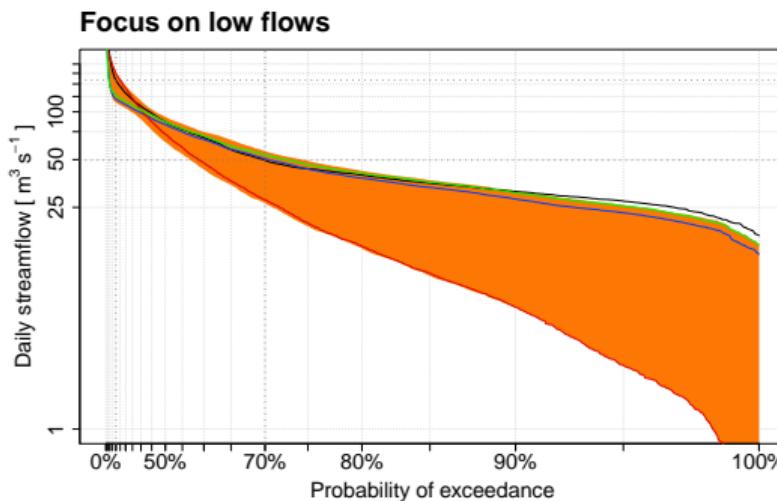
- **OF 1:** Daily high-medium flows using  $KGE(Q)$ .
- **OF 2:** Daily low flows using  $KGE_{lf}(Q)$ , a specific metric proposed by Garcia et al. (2017) .



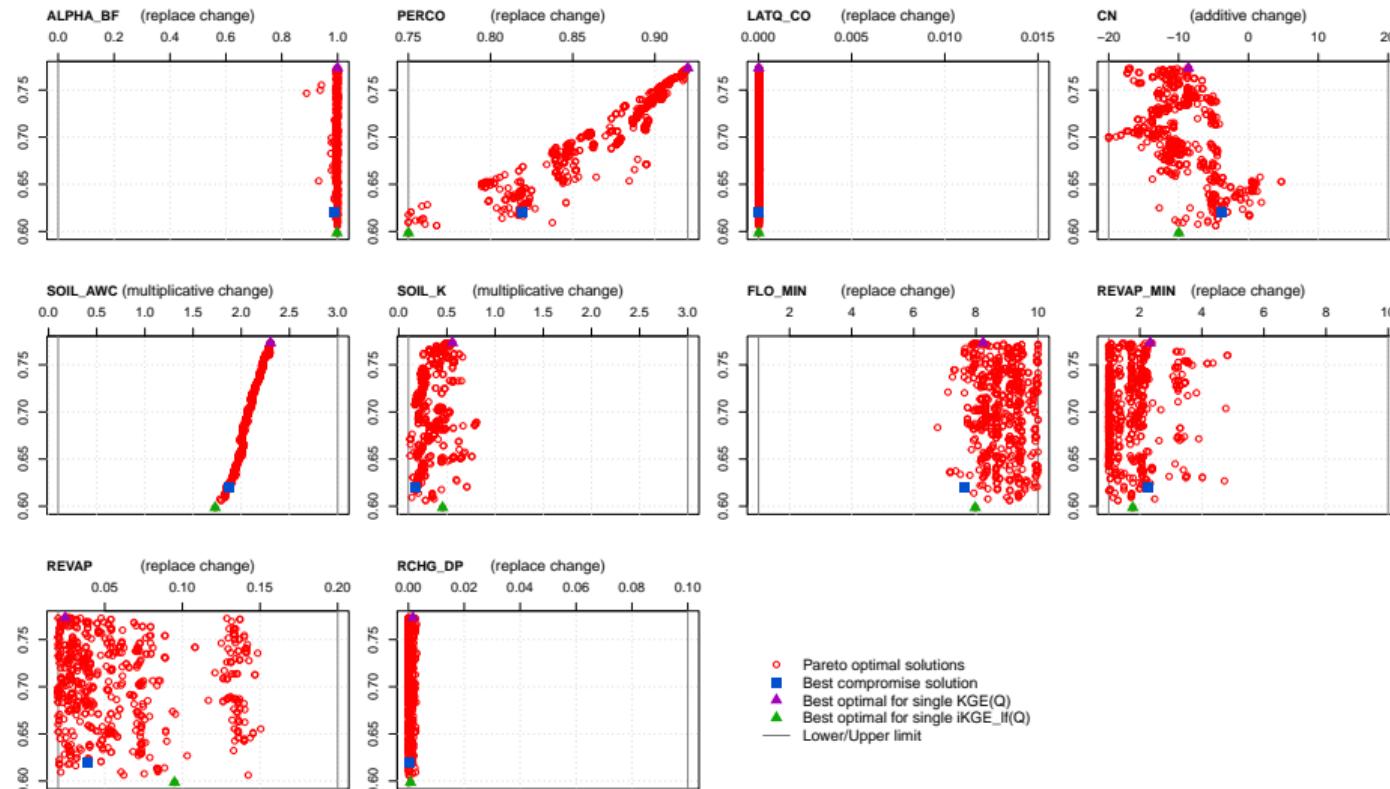
Legend in graph:

- **Observed:** observed daily discharges.
- **Simulated (best compromise):** discharges obtained in SWAT+ with a single point of the POF, which balances the two OF.
- **POF envelope:** Uncertainty bands encompassing all simulations derived from the POF.

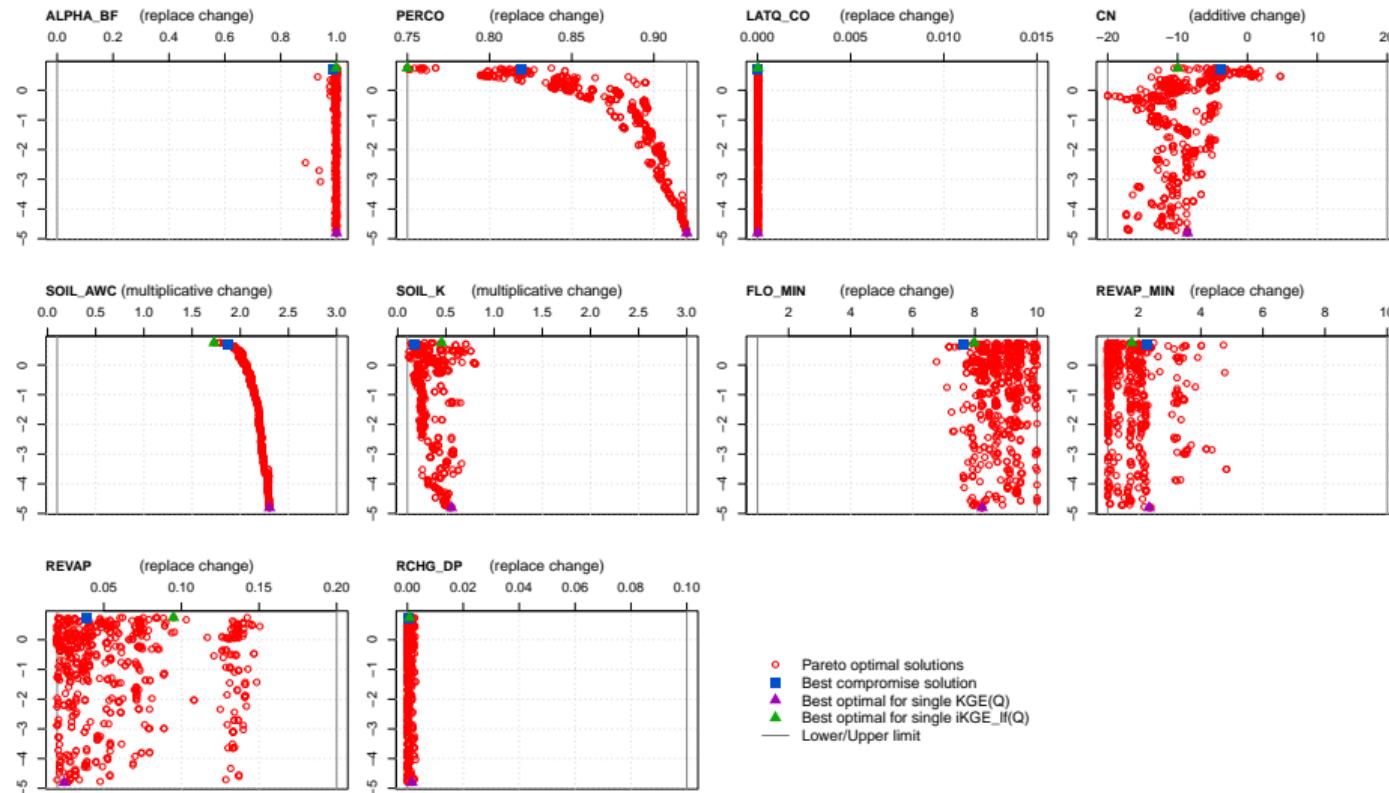
# Example 1: Flow duration curves



# Example 1: Dottyplots for $KGE(Q)$



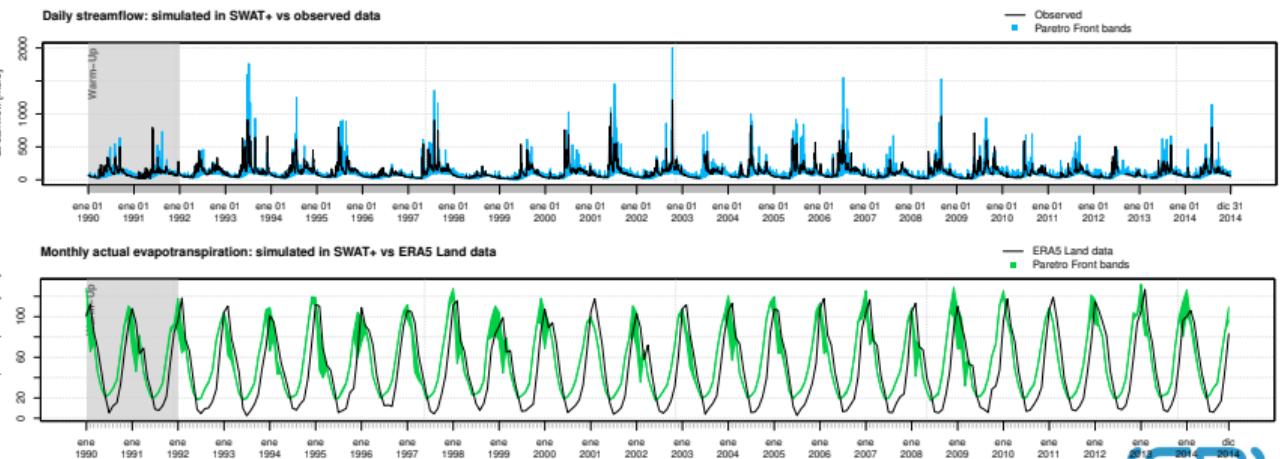
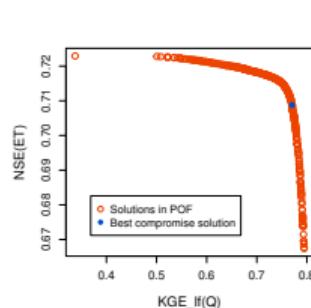
# Example 1: Dottyplots for $KGE_{lf}(Q)$



- Pareto optimal solutions
- Best compromise solution
- ▲ Best optimal for single  $KGE(Q)$
- ▲ Best optimal for single  $iKGE_{lf}(Q)$
- Lower/Upper limit

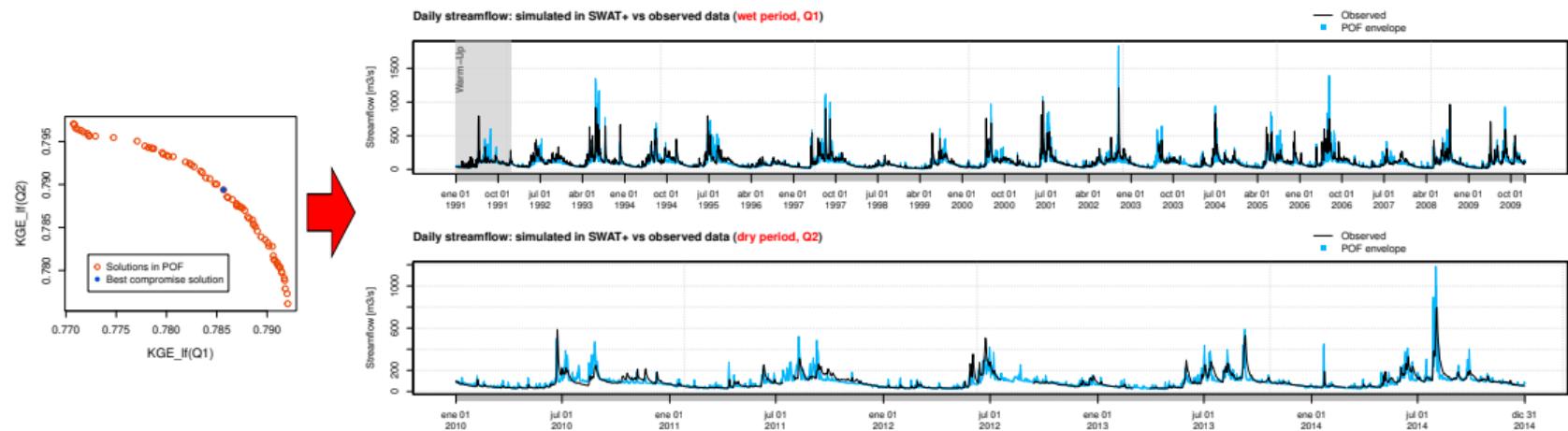
## Example 2: Multi-variable calibration

- **OF 1:** Daily low flows using  $KGE_{lf}(Q)$ .
- **OF 2:** Monthly actual evapotranspiration using Nash-Sutcliffe efficiency ( $NSE$ ).



## Example 3: Multi-period calibration

- **OF 1:** Daily low flows using  $KGE_{lf}(Q)$  for a wet period (1992-2009).
- **OF 2:** Daily low flows using  $KGE_{lf}(Q)$  for a dry period (2010-2014).



(CR)<sup>2</sup>

# Conclusions

- hydroMOPSO is a new and flexible R package designed for **reproducible multi-objective optimisation of any real-world environmental/hydrological model**.
- hydroMOPSO can be **easily coupled** with any environmental/hydrological model.
- Three case studies with SWAT+ demonstrated its versatility to take advantage of different types of information contained in the input data.
- Can be **easily run in parallel** (without modifying the SWAT source code) → important time saving !.
- The package's documentation and a series of tutorials are available at <https://cran.r-project.org/package=hydroMOPSO>.
- We **invite to the SWAT and SWAT+** community to explore the potential of hydroMOPSO for analysing the **parametric and predictive uncertainty** of complex MOO problems.



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# hydroMOPSO performance evaluation

## Benchmark functions

- Three well-known DTLZ problems: DTLZ1, DTLZ2 and DTLZ3 (Deb et al., 2005), each one with three objectives.
- Kursawe function: with two objectives (Kursawe, 1991).

## Calibration problems (study zone required)

- GR4J calibration: MOO calibration of GR4J (Perrin et al., 2003) hydrological model, with two objectives.
- TUWmodel calibration: MOO calibration of HBV-based TUWmodel (Parajka et al., 2007), with two objectives.

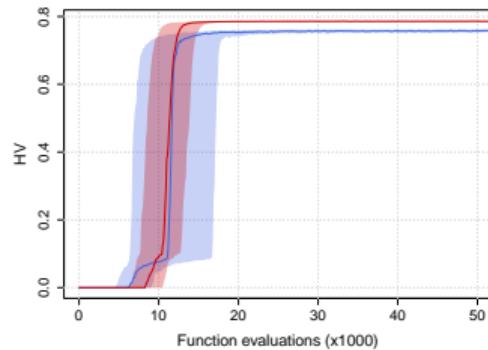
## Basic details:

- Identify the **Pareto Optimal Front (POF)**
- Use the **hypervolume (HV)** (Zitzler and Thiele, 1999) to assess the **accuracy** and **diversity** of the POF.
- Use the **generational distance (GD)** (Zitzler and Thiele, 1999) to assess the **diversity** of the POF.
- Evaluate the **number of model runs** required to achieve the POF → **efficiency**.

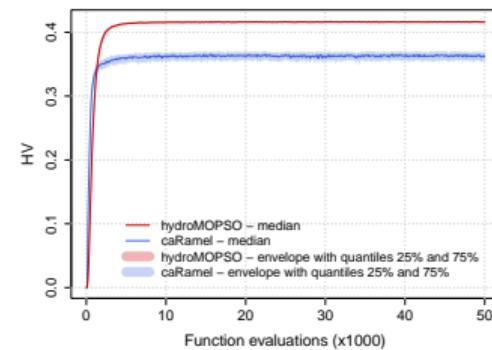


# Performance evaluation

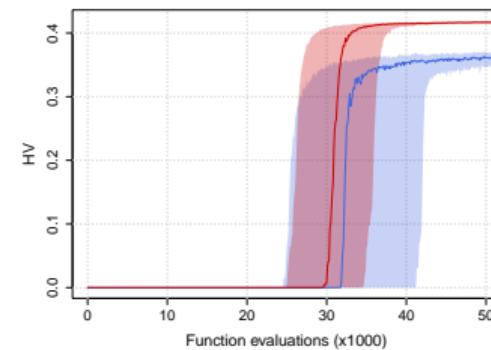
a) DTLZ1  
Benchmark problem



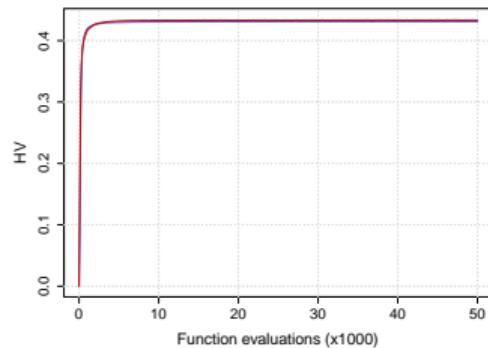
b) DTLZ2  
Benchmark problem



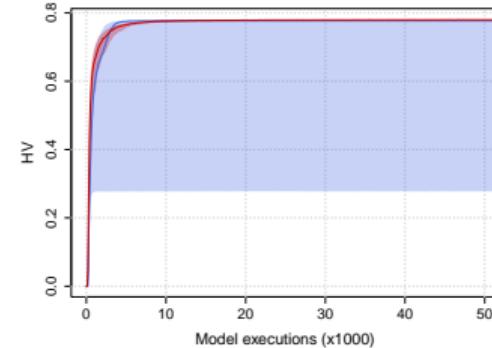
c) DTLZ3  
Benchmark problem



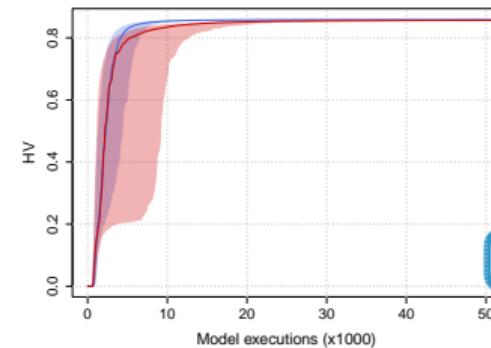
d) Kursawe  
Benchmark problem



e) GR4J (KGE'+iKGE'G)  
Real-world problem

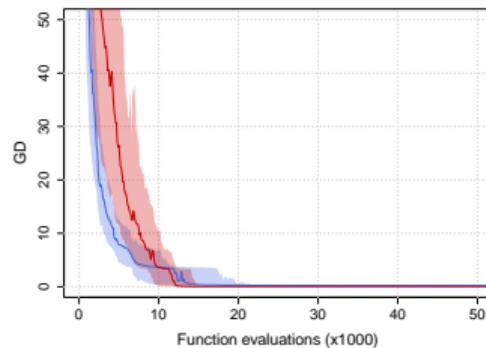


f) HBVbased-10param (KGE+iKGE'G)  
Real-world problem

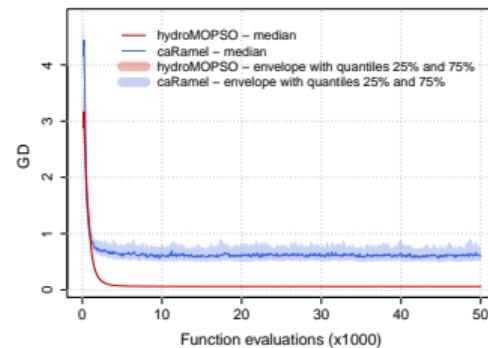


# Performance evaluation

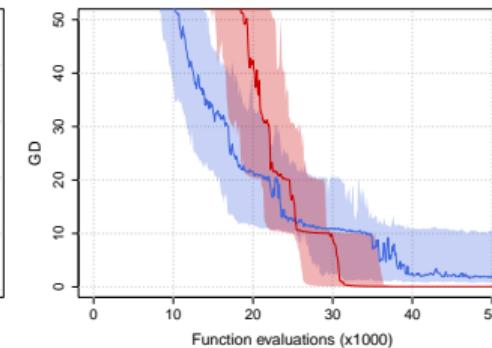
a) DTLZ1  
Benchmark problem



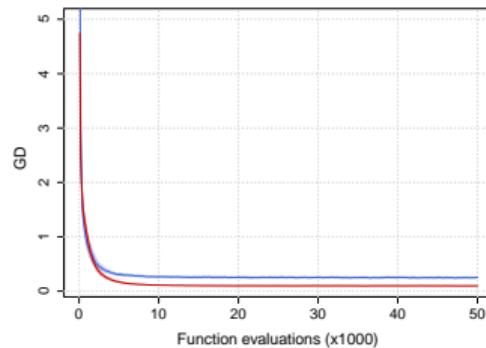
b) DTLZ2  
Benchmark problem



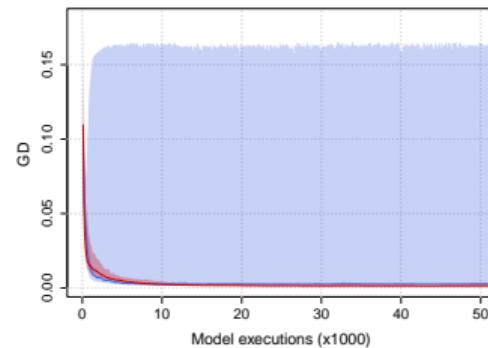
c) DTLZ3  
Benchmark problem



d) Kursawe  
Benchmark problem



e) GR4J (KGE'+iKGE'G)  
Real-world problem



f) HBVbased-10param (KGE+iKGE'G)  
Real-world problem

