### Estimating Plant Available Water for General Crop Simulations in Almanac/APEX/EPIC/SWAT

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### **Plant Available Water**

• A critical variable in the plant growth modules of Almanac, EPIC/APEX and SWAT is soil moisture.

 Plant Available Water is a fundamental driver of the plant sub models.

PAW is computed from the difference between
Field Capacity and Wilting Point (PAW = FC-WP).

### **Soil Data for Modeling**

- All four models use soils data stored in the STATSGO and SSURGO databases and National Soil Characterization Laboratory database.
- Data are stored by horizon.
- FC & PW are horizon-specific fields in these databases.



# There are some inconsistencies in the these databases:

- The survey, analytical and reporting methods and standards have changed since the first soil data were collected in 1942, but the databases use the original results;
- b. There are real differences between variables of similar soils depending on when and where they were collected.

### Leading to problems ...

 Output from simulations using different soils may be confounded with the changes in survey, analysis or recording methods that have evolved over 70 years.

• Plant (crop) growth is an important driver of soil evolution.

• Flaws in the plant growth projections can have profound effects on the conclusions drawn from model scenarios.

### **Solution Part 1**

• USDA-NRCS developed a database of 39,366 records of soil field capacity (FC) and wilting point (WP) in relation to soil texture (%Clay & %Sand) and organic carbon (%OC).

 Compare current model soil conditions against the reference set, and

Compute Plant Available Water (PAW = FC – WP) for use in plant growth models.

### **Solution Part 2**

Attilla Nemes\* developed a "brute force" Nearest Neighbor method for finding FC and WP from %Clay, %Sand, %OC using the NRCS database:

- Calculate the Euclidian distance between target and reference points;
- Sort the distances in ascending order;
- Average the response variables (FC & WP) for the *N* nearest neighbors.

\* Nemes et al. Soil Sci. Soc. Am. J. 70:327–336 (2006); Vadose Zone J. 5:1222–1235 (2006).

#### **Nearest Neighbor vs. Computed PAW**

The Nearest Neighbor method gives better estimates than the computational process methods of Baumer et al. (1994) and Rawls et al. (1991), based on RMSE tested using 1054 different soils not in the database.

Plant Available Water Rawls

Plant Available Water Baumer

Plant Available Water kNN





Unfortunately, the nearest neighbor method is very slow: it takes approximately 14X as long as the computational methods:

#### Benchmarks for 1054 40-yr Simulations

| Constant Inter   | Hrs | Mins | Secs  | Secs/run | Runs/min |
|------------------|-----|------|-------|----------|----------|
| Baumer (1994)    | 0   | 14   | 42.68 | 0.413    | 145.3    |
| Rawls (1991)     | 0   | 15   | 9.14  | 0.425    | 141.1    |
| Nearest Neighbor | 3   | 22   | 31.27 | 5.683    | 10.6     |

Rawls et al. (1991) Advances in Soil Science **16**:213-234. Baumer et al. (1994) MUUF v2.14 User's Manual. USDA-NRCS.

### The K-D Tree Binary Search

A solution is to continue to use the nearest neighbor method, but use a non-parametric technique called K-D Trees\* to find the nearest neighbors in *K*-dimensions more efficiently.

K-D Tree is a binary search method in K < 20 dimensions that operates in Klog N time.

\* Friedman et al. (1977) ACM Trans. Math. Soft. B:209-226.

### Comparing NN & K-D Tree:



## How the K-D Tree Compares ...

#### **Benchmark Time**

|                          | Hrs | Mins | Secs  | Secs/run | Runs/min |
|--------------------------|-----|------|-------|----------|----------|
| Baumer (1994)            | 0   | 14   | 42.68 | 0.413    | 145.3    |
| Rawls (1991)             | 0   | 15   | 9.14  | 0.425    | 141.1    |
| Norfleet (unpubl.)       | 0   | 15   | 15.11 | 0.428    | 140.2    |
| Nearest Neighbor         | 3   | 22   | 31.27 | 5.683    | 10.6     |
| KD-Tree (Friedman 1977)* | 0   | 21   | 10.29 | 0.594    | 101.0    |

•Time to build K-D tree: 0.156 sec Friedman et al. (1977) ACM Trans. Math. Soft. B:209-226 Rawls et al. (1991) Advances in Soil Science **16**:213-234. Baumer et al. (1994) MUUF v2.14 User's Manual. USDA-NRCS.

### Conclusions

- K-D Tree method for looking up soil properties is effective and efficient.
- Lookup tables are a viable means of "filling in" missing values in databases.
- Are there other properties that could be looked up like this?

