Improvement of SWAT Auto-Calibration for Accuracies in High and Low Flow Regime using K-means Clustering Algorithm





Improvement of SWAT Auto-Calibration for Accuracies in High and Low Flow Regime Using K-means Clustering Algorithm

2010 International SWAT Conference August 4, 2010

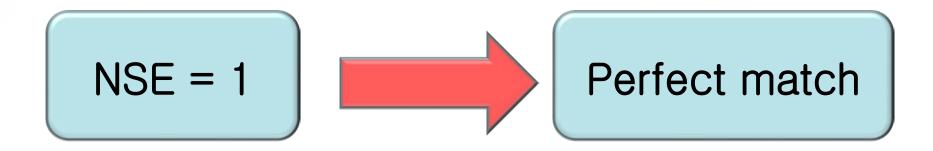
Hyunwoo Kang, Youn Shik Park, Jonggun Kim, Won Seok Jang, Ji Chul Ryu, Nam Won Kim, Dong Su Gong, Kyoung Jae Lim

Kangwon National University

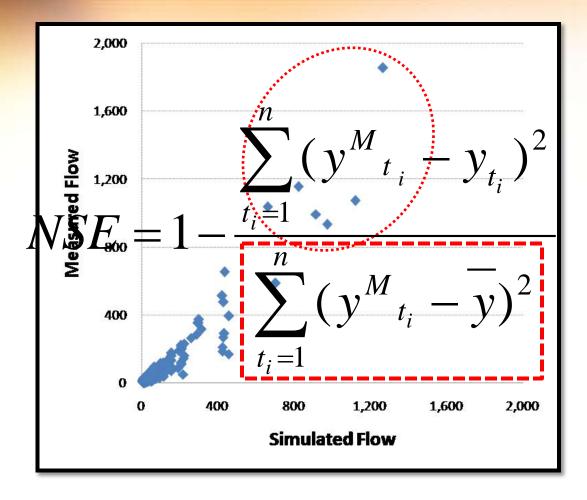
NY NY YAR

Kangwon National University

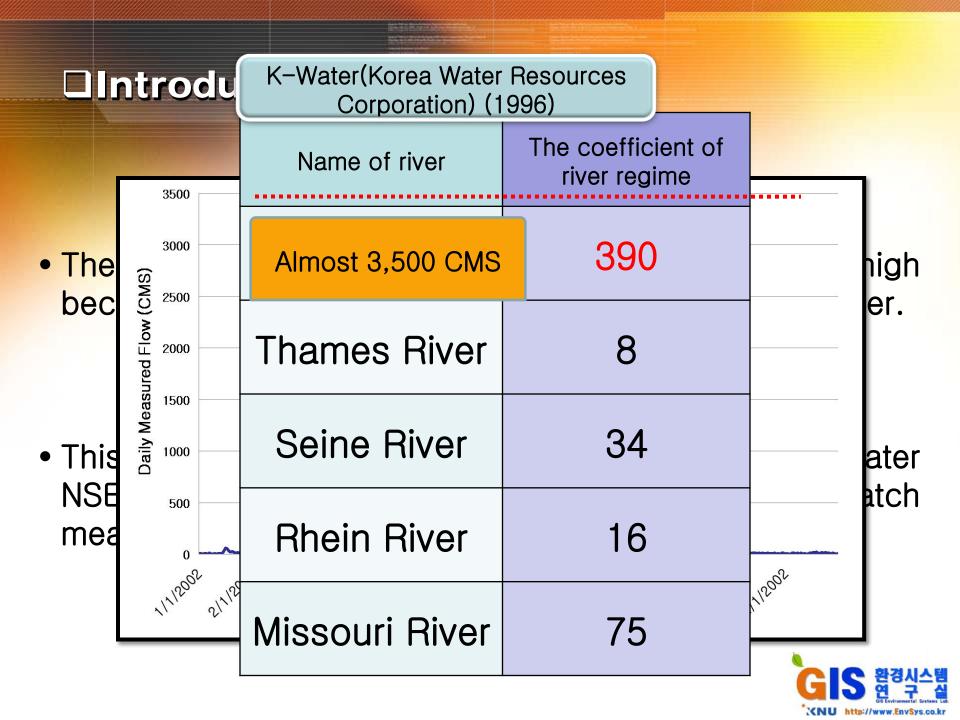
Nash and Sutcliff coefficient = NSE











SWAT auto-calibration

Parameter solution (Parasol)

Best parameter



Parameter solution (Parasol)

Goal function = NSE

It has a many chances to make a problem!!



K-means clustering algorithm

Simplest algorithm that solve the well known clustering problem



Objectives of this study

 To modify SWAT Auto-calibration using K-means clustering algorithm to improve accuracy in flow estimation for all flow regime

 To evaluate enhanced SWAT Auto-calibration module developed with K-means clustering algorithm by applying it to study watershed



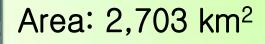
Two SWAT auto-calibration modules

 SWAT auto-calibration using Parameter Solution (Parasol) in current SWAT 2005 engine
 -> Original auto-calibration

 Enhanced SWAT Auto-calibration module using K-means algorithm -> K-means auto-calibration







Forest: 89.6 %

Agricultural: 5.3 %



Development of K-means auto-calibration module and simple GIS interface



Weakness of Nash-Sutcliffe coefficient in evaluating flow simulation

Park et al., (2007)

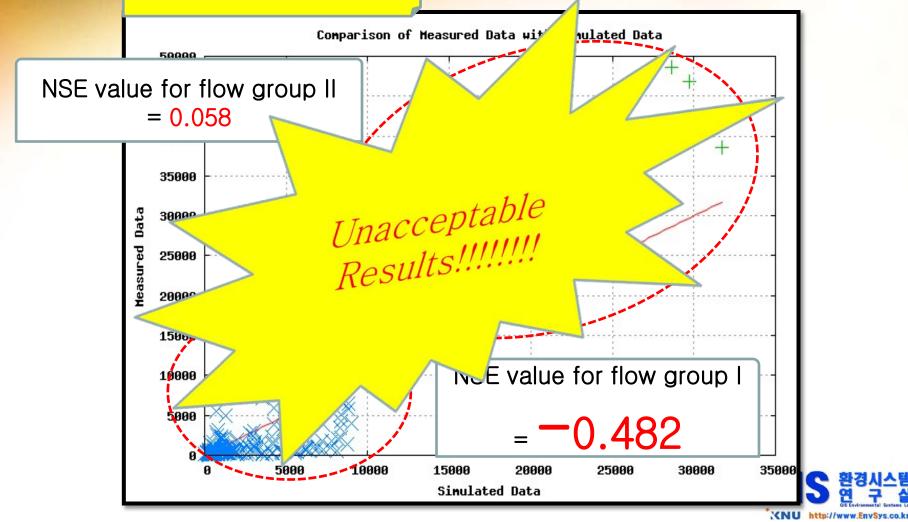
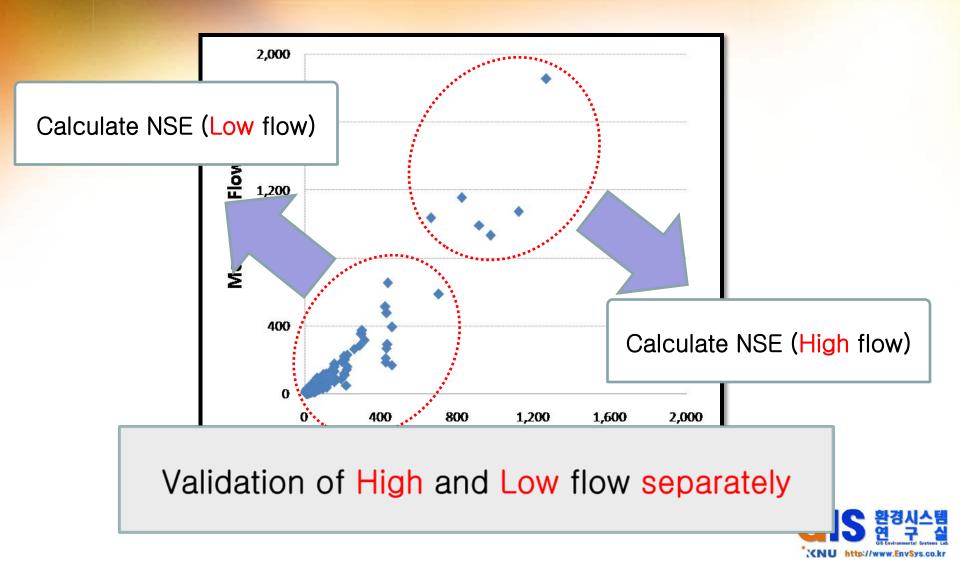


Image: Construction of auto-calibration using K-means algorithm



Objective function in Parasol

Parameter Solution (Parasol) Objective function => Sum of the squares of the residuals(SSQ)

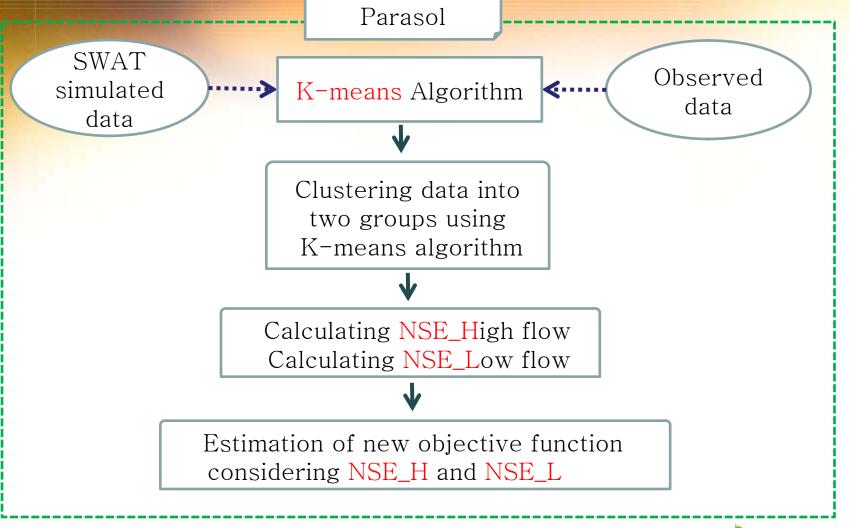
$$SSQ = \sum_{t_i=1}^{n} (y^{M}_{t_i} - y_{t_i})^2$$
$$NSE = 1 - \frac{SSQ}{\sum_{t_i=1}^{n} (y^{M}_{t_i} - \overline{y})^2}$$

$$y_{t_i}^{M} = Measured Data$$

 $y_{t_i} = Simulated Data$
 $\overline{y} = Average of$
measured Data
 $\sum_{t_i=1}^{n} (y_{t_i}^{M} - \overline{y})^2 = \overline{Y}$

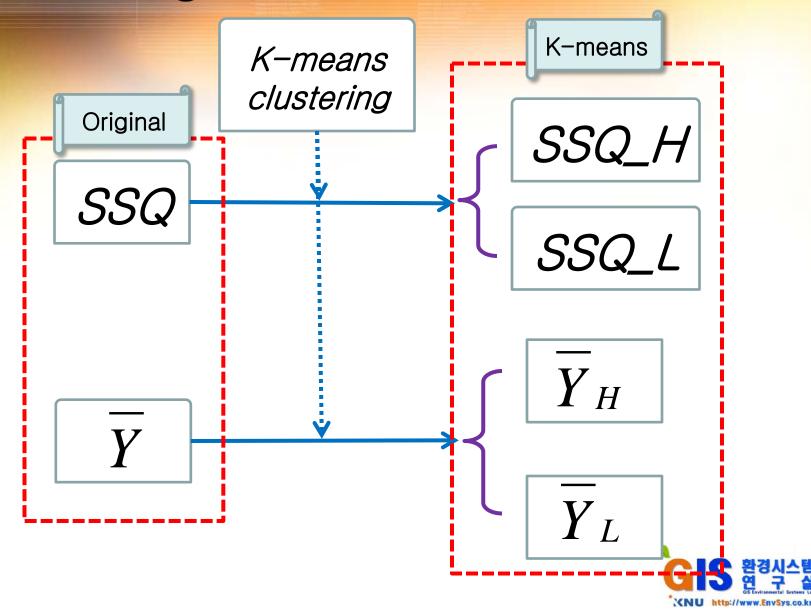
http://www.EnvS

Enhancement of Parasol algorithm using K-means clustering

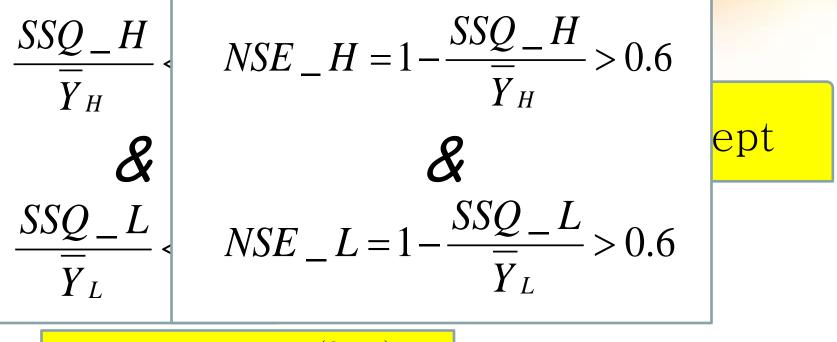




□Substitution of objective function considering NSE_H and NSE_L



□Substitution of objective function considering NSE_H and NSE_L

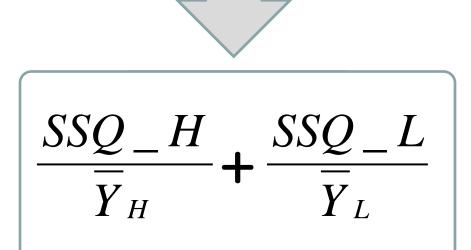


Donigan and	1 Love (2003	3)			
	Poor	Fair	Good	Very Good	
NSE for Daily Simulation	< 0.60	<mark>0.60</mark> ~ 0.70	0.70 ~ 0.80	> 0.80	

CNU http://www.EnvSys.co.kr

□Substitution of objective function considering NSE_H and NSE_L

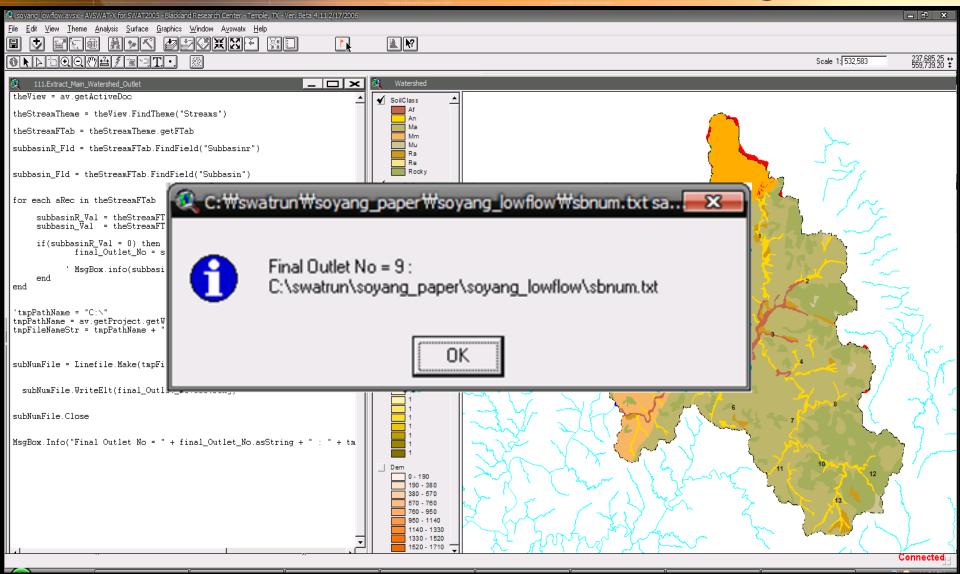
New objective function



NSE_H and NSE_L together



Determination of the number of main outlet in watershed automatically



KNU http://www.EnvSys.co.kr

Application of K-means auto-calibration



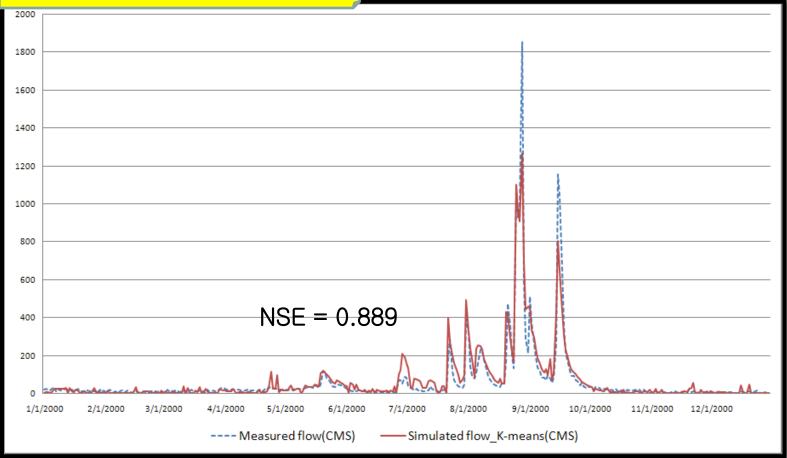
The parameters used in auto-calibration

Parameter	Description	Range
CN2	SCS runoff curve number for Moisture condition II	35 ~ 98
AHPAH_BF	Baseflow alpha factor	0 ~ 1
SURLAG	Surface runoff lag time	1 ~ 24
CH_N	Manning's "n" value for the main channel	-0.01 ~ 0.3
CH_K2	Effective hydraulic conductivity in main channel alluvium	-0.01 ~ 150
GW_DELAY	Groundwater delay	0 ~ 500
GW_REVAP	Groundwater "revap" coefficient	0.02 ~ 0.2
GWQMN	Threshold depth of water in the shallow aquifer required for return flow to occur	0 ~ 5000
SOL_AWC	Available water capacity of the soil layer	1 ~ 24



Comparison of SWAT auto-calibration

K-means Auto-calibration



The NSE values of Total flow are similar.



Comparison of SWAT auto-calibration

Type of Auto Calibra	ition	NSE - <mark>Tot</mark>	al Flow	NSE - I	ow Flow	NSI	E - High Flow
Donigan and Love (2003)			0.699			0.460	
		Poor	F	air.	Goo		Very Good
	ition	0.88	39	0.6	508		0.604
NSE for Daily Simulation	<	< 0.60 0.6		~ 0.70	0.70 ~ 0.80		> 0.80





 The NSE values from K-means auto-calibration are 0.608 and 0.604 for low and high flow regimes.

• However the NSE value for high flow from original auto-calibration is 0.460 (Poor calibration result).

Donigan and Love (2003)





 SWAT simulated flow using original auto-calibration may not match measured flow data because objective function in original auto-calibration is affected by big number.

• With K-means auto-calibration, developed in this study, would provide better estimation for all flow regimes.



Thank you for your Attention!!

